

AGRICULTURAL ROBOTIC SYSTEM FOR YEAR-ROUND AGRO-OPERATIONS

Autonomous robotic system for the entire plantation agrocycle



Pek Automotive's TECHNOLOGICAL FOUNDATION

R-WAVE 2D MP RADAR



The R-Wave 2D MP Radar is a **Radio Detection And Ranging system**, harnessing radio waves to reliably measure the surrounding space geometry, as well as speed and distances from objects, including those that may not be visible to the naked eye.

Moreover, the R-Wave 2D MP RADAR can determine the velocity of a moving object and is used for navigation and flawless autonomous operation.

R-WAVE RTK



The R-Wave RTK, or **Real-Time Kinematic positioning**, is a sophisticated technology that significantly enhances the accuracy of GNSS (Global Navigation Satellite System) positioning.

While conventional GNSS receivers, such as those relying on GPS, provide locational accuracy within a range of 2-4 meters, the RTK technology narrows this down to a remarkable Centimeter-level precision.

R-WAVE AUTONOMOUS



The R-WAVE Autonomous facilitates the autonomous operation of vehicles and robots within a pre-defined area. By harnessing the capabilities of R-WAVE RTK and 2D MP RADAR, along with reflectors, the system creates a detailed map of the area for subsequent repetitive tasks.

Once this map is drawn up, the vehicle can navigate autonomously without the use of RTK and GNSS signals, relying solely on the map, radar, and reflectors.

For operations outside permanent plantations, utilizing the GNSS and RTK system is advantageous, given its swift setup and ease of dismantling.

R-WAVE POWER



The R-Wave RPower is the **base technology system** that powers our vehicles. It enables endless configuration options for the development of custom special-purpose electric vehicles.



HOW it works?

Setting up the PeK Agrobot robotic agrosystem is simple and ensures reliable operation throughout the plantation's lifetime. Once deployed, it requires only minimal maintenance. Everything you need to streamline your field agro operations with effortless simplicity. Simple, just like counting 1-2-3.



BASE PLATFORM

Charge the Base Platform at the **Charging Station**, ensuring full operational readiness.





HINGED ATTACHMENTS

Secure the appropriate Hinged Attachment using the **Installation Carrier** for precise functionality.





TEROAIR

Transport with a B-category trailer, set parameters, attach tools, and start. Monitor remotely via TeroAir.

TeroAir is a mobile app for real-time monitoring and control, keeping users updated on Slopehelper's performance and events directly from their smartphones.



3 Easy Steps for **DEPLOYMENT**

With these quick setup steps, the machine is ready to deliver fully autonomous agricultural operations, optimizing efficiency and reducing labor costs for vineyard and orchard owners.

CLEAR THE FIELD FOR OPTIMAL NAVIGATION

Remove obstacles

such as fallen trees, broken wires, large stones, columns, and earth mounds that could obstruct the robotic system's movement.

INSTALL REFLECTORS FOR PRECISION

For plantations without metal pillars, install reflectors at the beginning of each row. These cost-effective plastic elements enhance radio locator precision, allowing accurate row detection for seamless automation. (Note: If metal pillars are present, reflectors are usually unnecessary.)

CREATE A GEOMETRICAL PLANTATION MODEL

Map the plantation **manually** using a meter or

Use an **advanced mapping system** for precise digital modeling, ensuring optimal robot navigation.

TWO ROBOTIC SOLUTIONS for every farmers needs

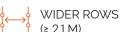




















GNSS DRIVE WITH OR WITHOUT GNSS



LESS COSTS





WARRANTY UP TO 5 YEARS



LOW ELECTRICAL VOLTAGE OF 48V



EASY TO USE



100% AUTONOMOUS



WORKING UP TO 14 HOURS



100% ELECTRIC



What is Shi slopehelper?

Slopehelper is a fully autonomous, electric agrosystem that replaces traditional farm machinery—delivering efficient, cost-effective, and sustainable field management.



HINGED ATTACHMENTS



ORCHARDS, VINEYARDS



WIDER ROWS (≥ 2,1 M)







HINGED ATTACHMENTS



































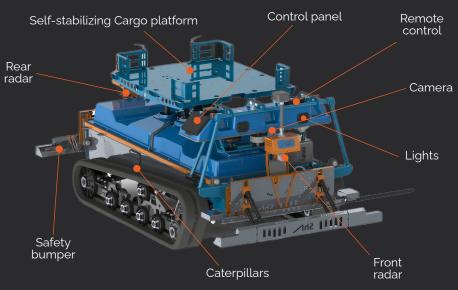




Main technical parameters of the Slopehelper Base Platform

PARAMETER	VALUE
Size of base platform (length x width x height)	2600 x 1610 x 1230 mm
Weight	1750 kg
Operation time	up to 12 hours (depends on instrument)
Number of operations	19
Maximum speed	5 km/h
Platform side inclination	± 35° in axial directions
Maximum slope operation	42°
Battery (maximum on-board voltage)	48V (based on EV48 FEV technology)
Charging time (speed charger)	8 - 10 hours (3,5 hours)
Safety system	Electromechanical bumpers and Collision avoidance system based on radiowave scanners

BASE PLATFORM PARTS





AGROCYCLE OPERATIONS

温 TREATMENT & PROTECTION

Turbo spraying on both sides of the passage with **DOUBLE-SIDED SPRAYER**



Autonomous fruit picking by 6 robotic manipulators with **FRUIT PICKER**

Autonomous grape cluster/branches harvesting with 4 robotic manipulators with **GRAPE PICKER**

Base platform conversion into a 8-worker harvesting or plantation service platform/combine with HARVESTING SET



NUL

Explore Slopehelper's

FULL AGROCYCLE CAPABILITIES

with specialized attachments for every season. Discover how it transforms your vineyard or plantation year-round.



WEED MANAGEMENT & MULCHING

String mulching in root zones and trunk cleaning for mature trees with SIDE TRIMMER

String mulching in root zones and trunk cleaning for young and mature trees with **ACTIVE SIDE TRIMMER**

Branches and grass mulching in root zones by horizontal knife flails with SIDE LAWN **MOWER**

Branches and grass mulching in passages by cutting-edge hammer flails with **DRUM MULCHER**

Soft branches and grass mulching in passages by horizontal elliptical knives with **LAWN MOWER**



PRUNNING & CANOPY TRIMMING

חחר

Rotary disk pruning of grapevine branches with PRE-PRUNER

Robotic branch cutting in vineyards and orchards using a scissor manipulator with PRUNER

Lateral and top tree cutting with columns' bypass in vineyards and orchards with HORIZONTAL-VERTICAL CUTTER

Single-pass all-sided row cutting in vineyards with **U-SHAPE CUTTER**



SOIL PREPARATION & MAINTENANCE

Rotary soil cultivation in root areas with **POWER HARROW**

Soil cultivation in passages using spiked disks with **NEEDLE HARROW**

Application of granular/pellet fertilizers or seed spreading with **FERTILIZER**

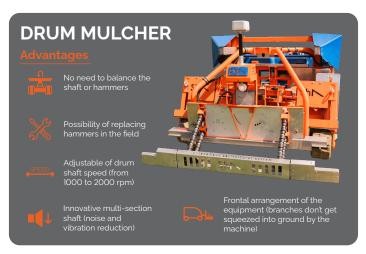
Plowing in passages and tilling in root zones with **PLOUGH**

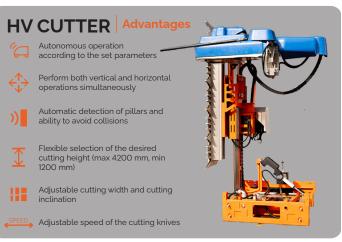


温源 LEAVES & FLOWERS CONTROL

Removing leaves from the grapevine canopy around the grapes with LEAF REMOVER

Flower removal in orchards to regulate harvest development with **BLOSSOM THINNER**











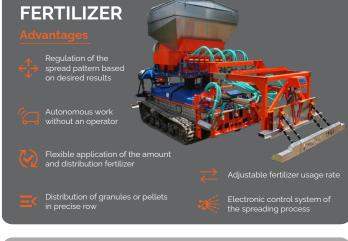




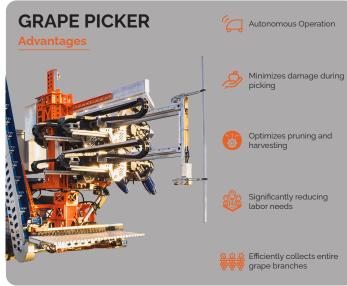


















Smarter, Faster, and More Efficient Than Conventional Harvesting

The Fruit Picker revolutionizes orchard harvesting by efficiently collecting fruit along one side of each tree row. Often, the harvested quantity exceeds a standard bin's capacity, requiring strategic unloading. Unlike manual platforms, which swap bins mid-row, the Slopehelper Fruit Picker completes the row smoothly—full bins are replaced at the end with a forklift, minimizing downtime and maximizing productivity. With careful planning, growers enjoy higher efficiency, smarter operations, and a faster harvest.

Bin Capacity Limit



Normally the fruits which can be collected on one side of the tree row doesn't fit into the standard agricultural bin. **End-of-Row Unloading**



The only option for unloading the full bin is to drive the machine until the end of the passage, where it can be taken out by a fork lift and replaced by an

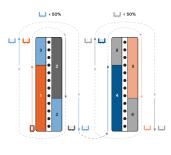
Travel Time Consideration

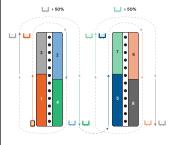


This movement with a full basket will take time and not contribute to the operation, so the strategy must be selected wisely.

Fruitpicker Strategy: The optimized path and smart sequence of operations

empty one.





The Fruit Picker overcomes the limitations of traditional harvesting by minimizing idle travel time and optimizing bin unloading.



What is Ah # AGILEHELPER?

Agilehelper is the smart, cost-efficient robot for small to medium vineyards. It ensures precision, reliable performance, and cuts labor costs.

Agilehelper Robotic System offers two machines: **GRASSFIGHTER** and **DOUBLE-SIDED SPRAYER**



INTEGRATED TOOLS



VINEYARDS, BUSHES



NARROWER ROWS (≥ 1,7 M)







Advantages



No need to balance the shaft or hammers



Frontal arrangement of the equipment (branches don't get squeezed into ground by the machine)



Possibility of replacing hammers in the field



Adjustable of drum shaft speed (from 1000 to 2000 rpm)



Innovative multi-section shaft (noise and vibration reduction)

DOUBLE-SIDED SPRAYER

Advantages



1 operation - SPRAYING



Flexible spraying between rows



High spray quality maintained regardless of pressure or fan speed



Fan elevation and angle adjust for trees up to 4 meters



Precision Spraying regardless of wind or conditions



Adjustable Liquid Use with a minimum of 150 liters/ha



HV CUTTER

Advantages



Automatic detection of pillars and ability to avoid



Perform both vertical and horizontal operations simultaneously



Adjustable speed of the cutting knives



Autonomous operation according to the set parameters



Adjustable cutting width and cutting inclination



POWER HARROW

Advantages



High-Precision Cultivation with dual blades



Versatile Functionality in combination with the autonomous vehicle



Specifically targets the root zones

Technical Specifications - Grassfighter

DIMENSIONS	VALUE
Height	1760 mm
Length	3960 mm
Width	1245 mm
Weight	1800 kg
WORKING DIMENSIONS	VALUE
Working slopes	Up to 38°
Minimum speed	0,5 km/h
Maximum speed	4 km/h
Maximum drive	10 kW
ELECTRIC SYSTEM	VALUE
Battery	48 V (LiFePO)
Battery Capacity	28,7 kWh
Working hours between charging	8-12 h (depending on the type of operation)
Charging time	8-10 h
GENERAL SPECIFICATIONS	VALUE
Control	Onboard computer Remote controller Autonomous Navigation system
Safety system	Electromechanical (additional collision avoidance system based on radio wave scanners)
Caterpillars	200 x 72 x 44
Gearbox stages	2 (1 chain, 1 worm gearbox unit)
Brake system	Band brake (air release)
Additional features	True-autonomous (no need GNSS) High resolution touch sensor

Technical Specifications - Double-sided sprayer

DIMENSIONS

Gearbox stages

Brake system

VALUE

Height	1750 mm
Length	3840 mm
Width	1245 mm
Weight	1400 kg
WORKING DIMENSIONS	VALUE
Working slopes	Up to 38°
Minimum speed	0,5 km/h
Maximum speed	4 km/h
Maximum drive	10 kW
ELECTRIC SYSTEM	VALUE
Battery	48 V (LiFePO)
Battery Capacity	28,7 kWh
Working hours between charging	8-12 h (depending on the type of operation)
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2 (1 chain, 1 worm gearbox unit)

Band brake (air release)

PEK AGROBOTS





Listening to growers' needs to deliver solutions that respect the earth and people

PeK Agrobots outperform grower expectations: They have increased performance, reduced labor and operational costs, and eliminated field emissions.

With labour in short supply, healthy food in high demand, and climate change at critical levels, **Pek Agrobots has a very practical answer**: autonomous, zero-emission machinery that keeps plantations clean, healthy, and productive.

Founded on commitment, innovation, and responsibility, we design visionary, dependable, and ecologically sensitive solutions.

labor shortages!

With PeK Agrobots, agriculture enters a more sustainable future: decreasing drudgery at the workplace, improving working conditions, and maintaining the natural environment intact.

Our mission goes beyond technology; it's about empowering farmers towards embracing a smarter, greener future. We guarantee that every PeK Agrobot is built with an assurance of balanced ecosystems, thriving agricultural communities, precision engineering, and continuous innovation to respect nature.

Pek Agrobots redefine modern farming by merging intelligence, autonomy, and sustainability; it takes challenges as an opportunity for growth, efficiency, and being in tune with the planet.

needed!



traditional equipment!



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